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State Diagram



C++ Object Oriented Programming

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NTOU CS

Contents

- ❖ Introduction to object states
- ❖ Interface vs. States
- ❖ Object with States
- ❖ Intuitive Implementation
- ❖ Explicit States
- ❖ State Diagram
- ❖ Systematic Implementation of the State Diagram
- ❖ Modification of the Design
- ❖ Design with the “State” Pattern

Introduction

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- ★ I can answer the phone, but whether I answer or not depends on I am **busy or not** when the phone rings.

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- ★ A television set usually has a couple of control buttons, e.g. volume up/down, channel up/down, setup, power etc.

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Introduction (cont'd)

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1. A very simple object might have a fixed state such that its behavior is all the way consistent.
 2. The timing of messages to an object with various internal states is important and determines how an object responds.
 3. Usually the states of an object cannot be observed directly from outside. The messages an object received up to now affect its current state and therefore its future behaviors.

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Object with States

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class NetCommStream {  
public:  
    void open();  
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private:  
    ...  
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Correct usage:

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Incorrect usage:

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NetCommStream obj;  
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Intuitive Implementation

- ✧ Using *bool* variables to keep various kinds of states

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void open() {  
    if (!m_fOpen) {  
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Two flags are used in the above implementation. **4 different states?**

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implicit and vague

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Explicit State

- ✧ Two *bool* variables `m_fOpen` and `m_fConnected` define 4 legal states

Explicit State

- ✧ Two *bool* variables `m_fOpen` and `m_fConnected` define 4 legal states; but *only 3 of them are meaningful* to this application

State Diagram

Closed

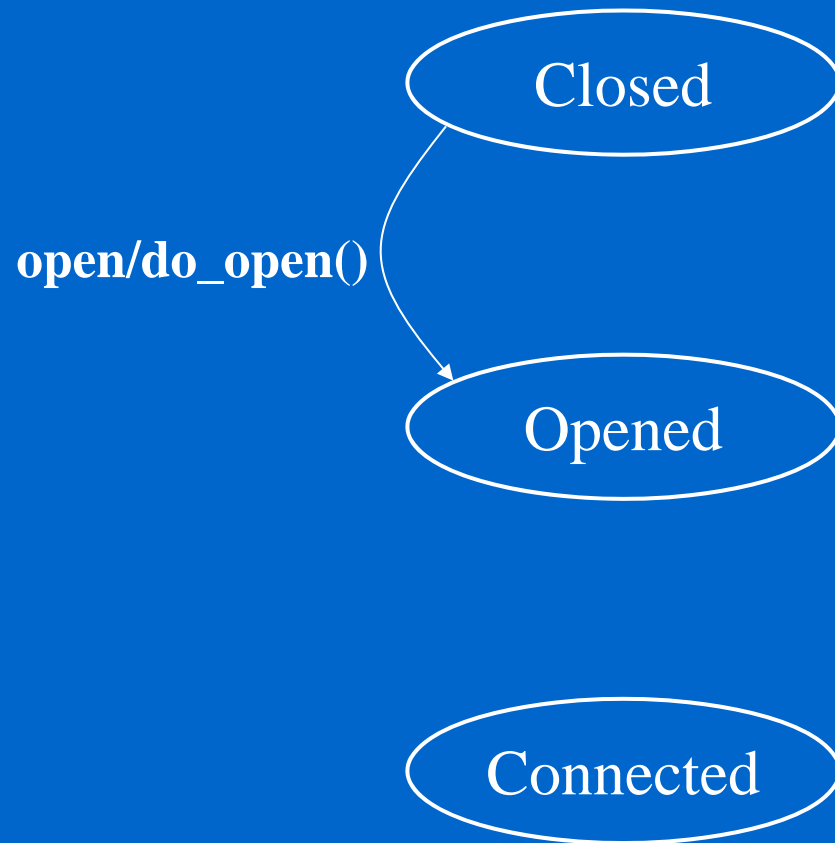
Opened

Connected

Consider ALL possible events at the outgoing branches of each state.

Finite State Machine

State Diagram

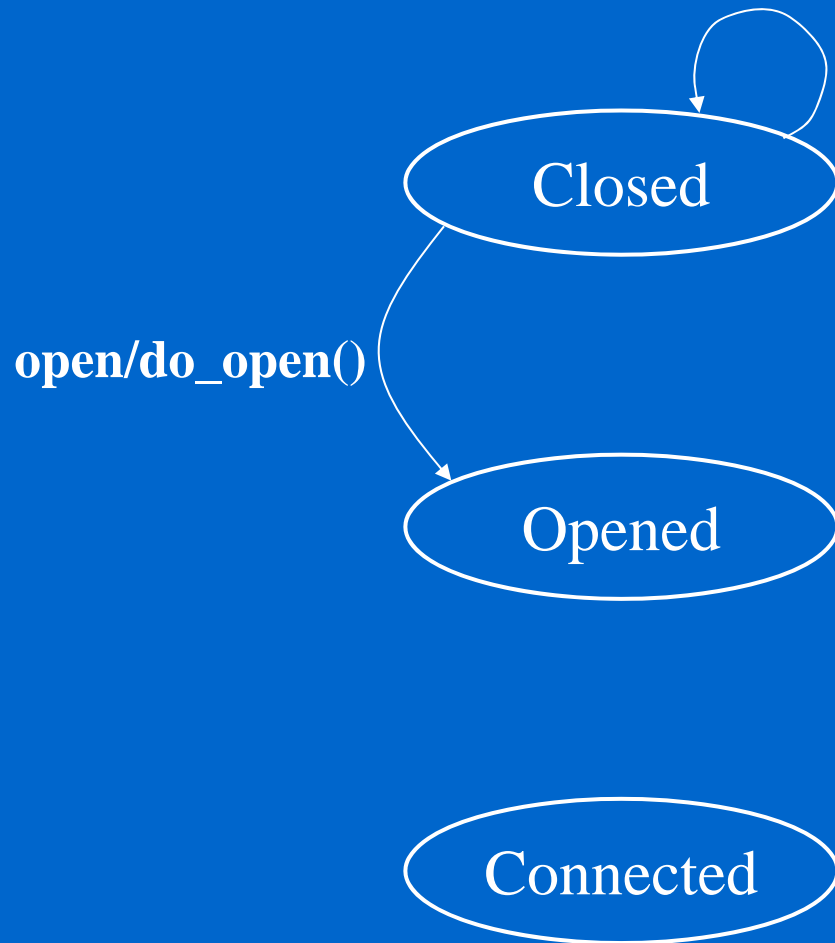


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Finite State Machine

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connect,read,write,disconnect,close/NOP

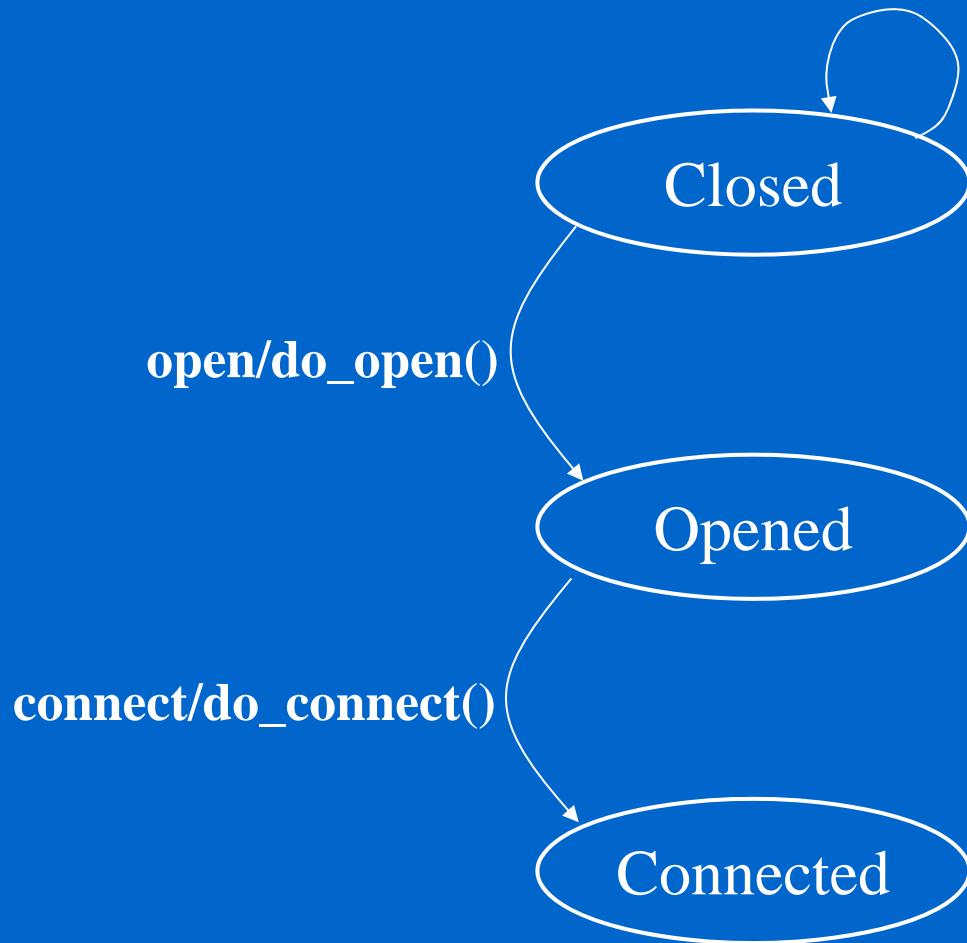


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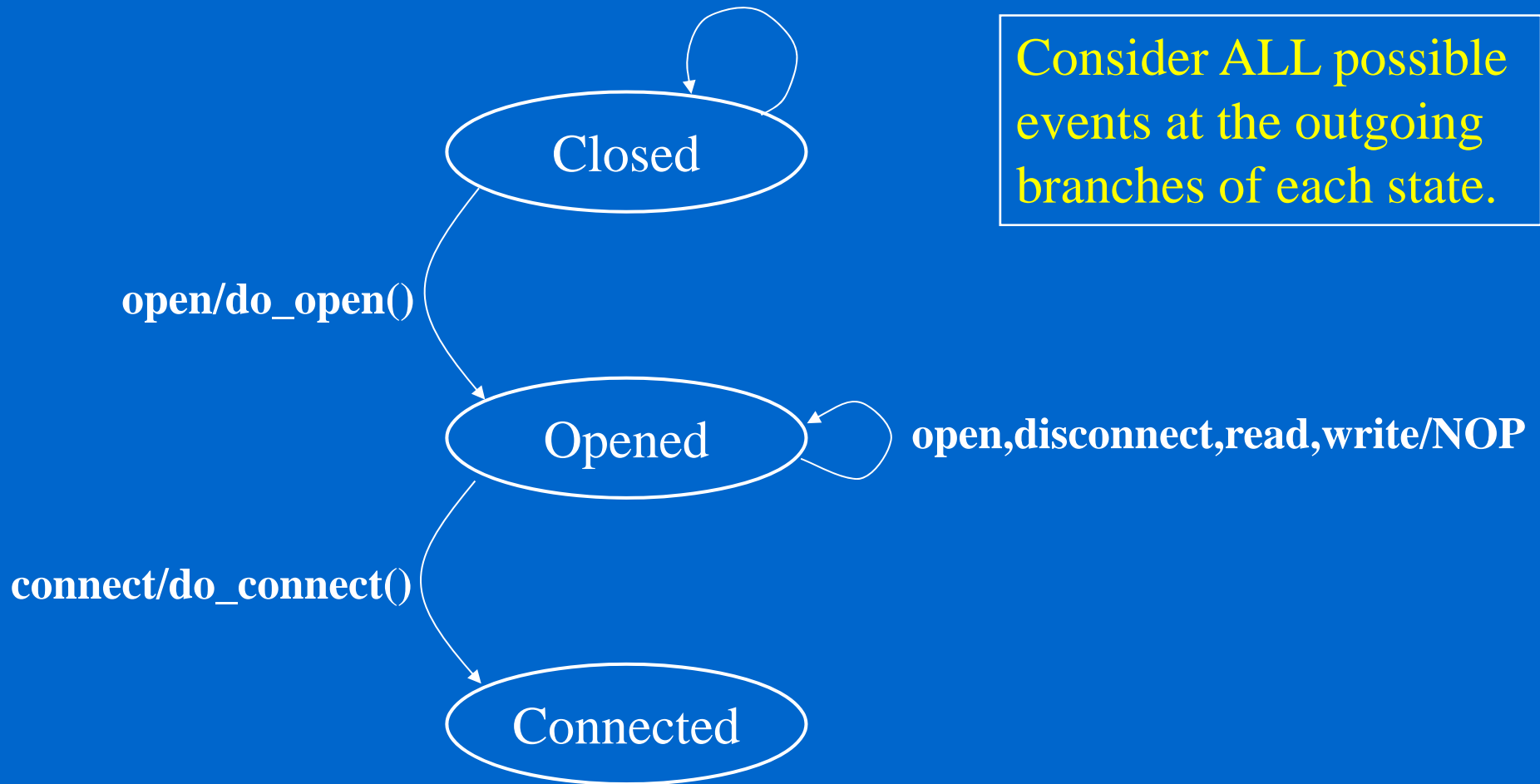


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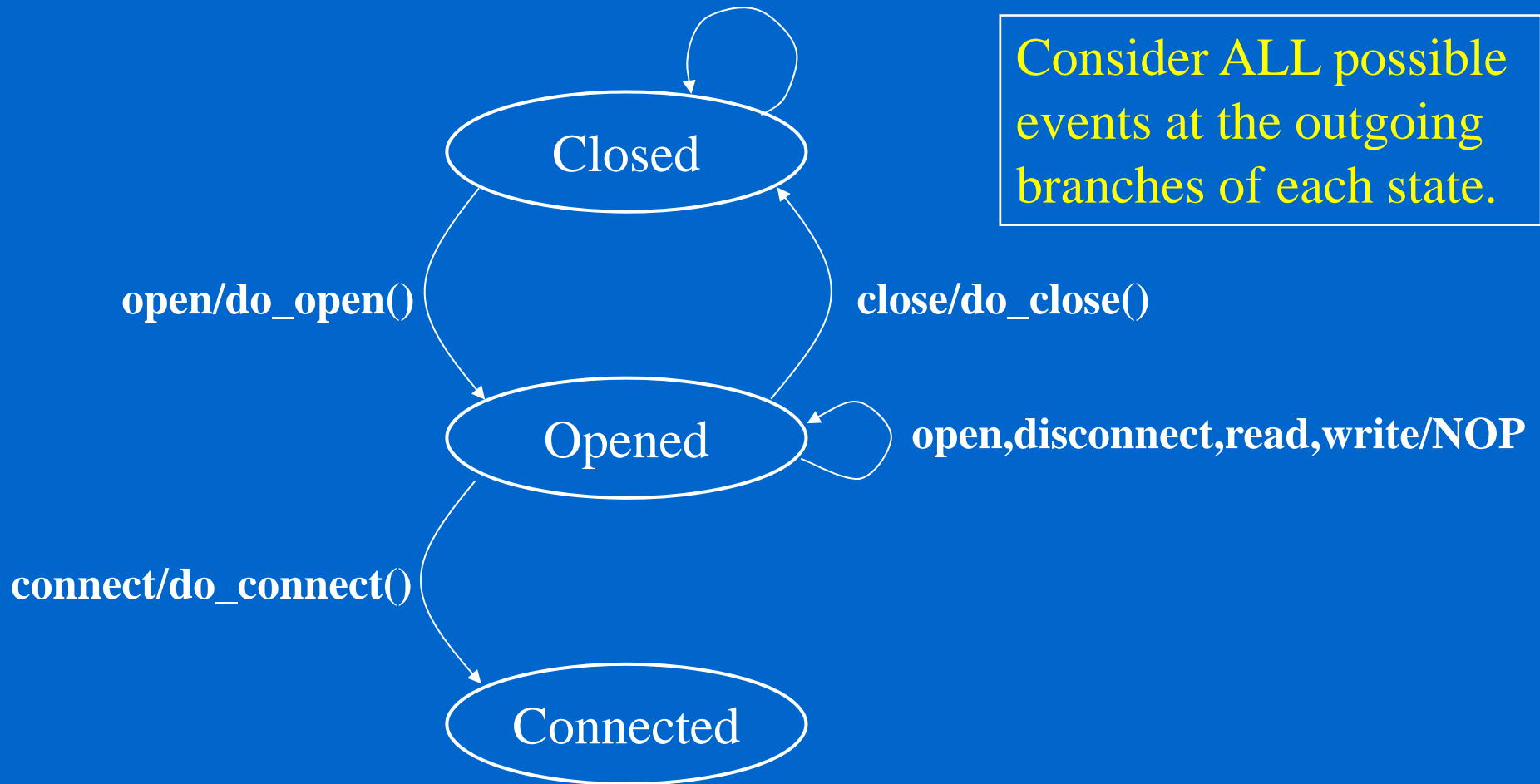
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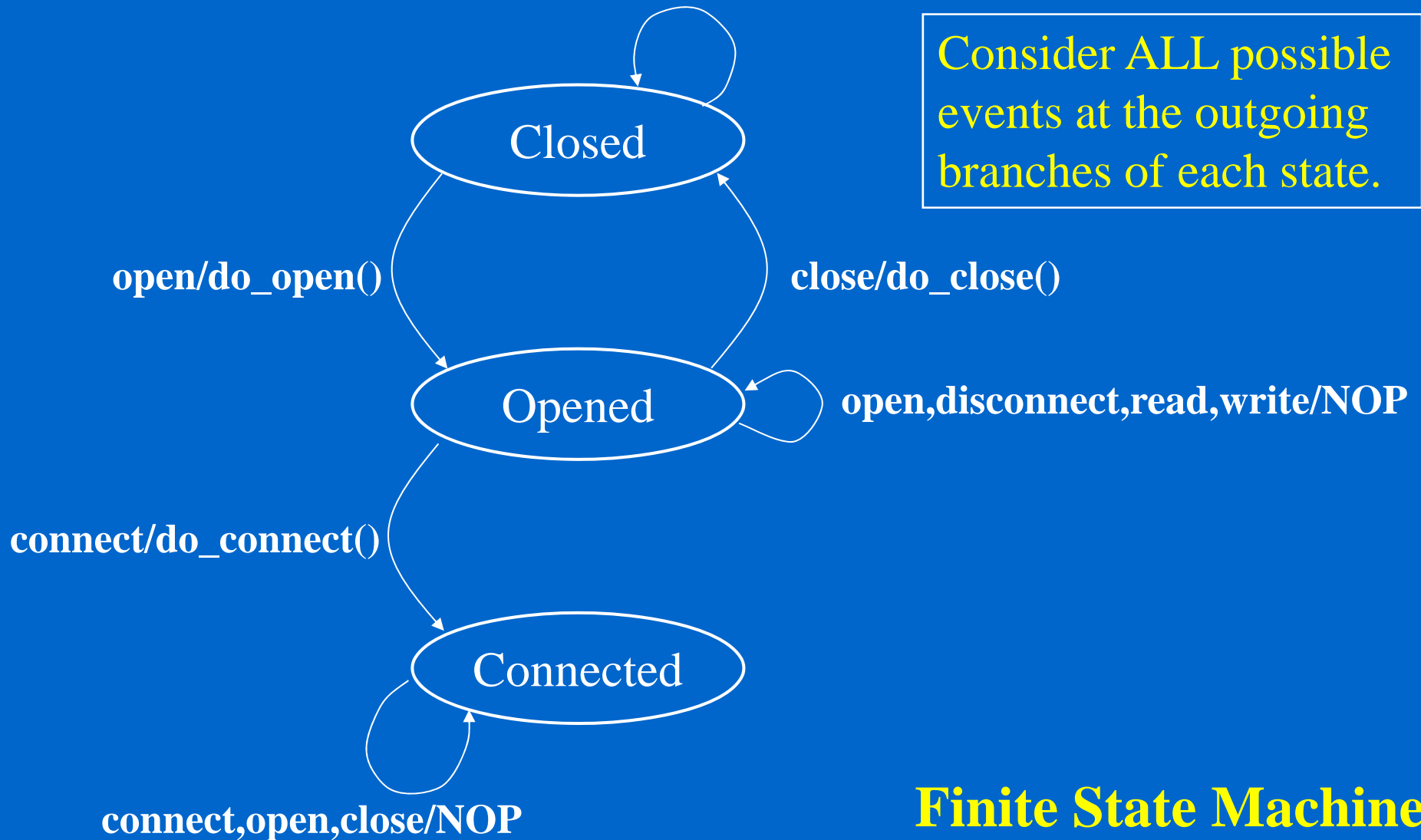
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Finite State Machine

State Diagram

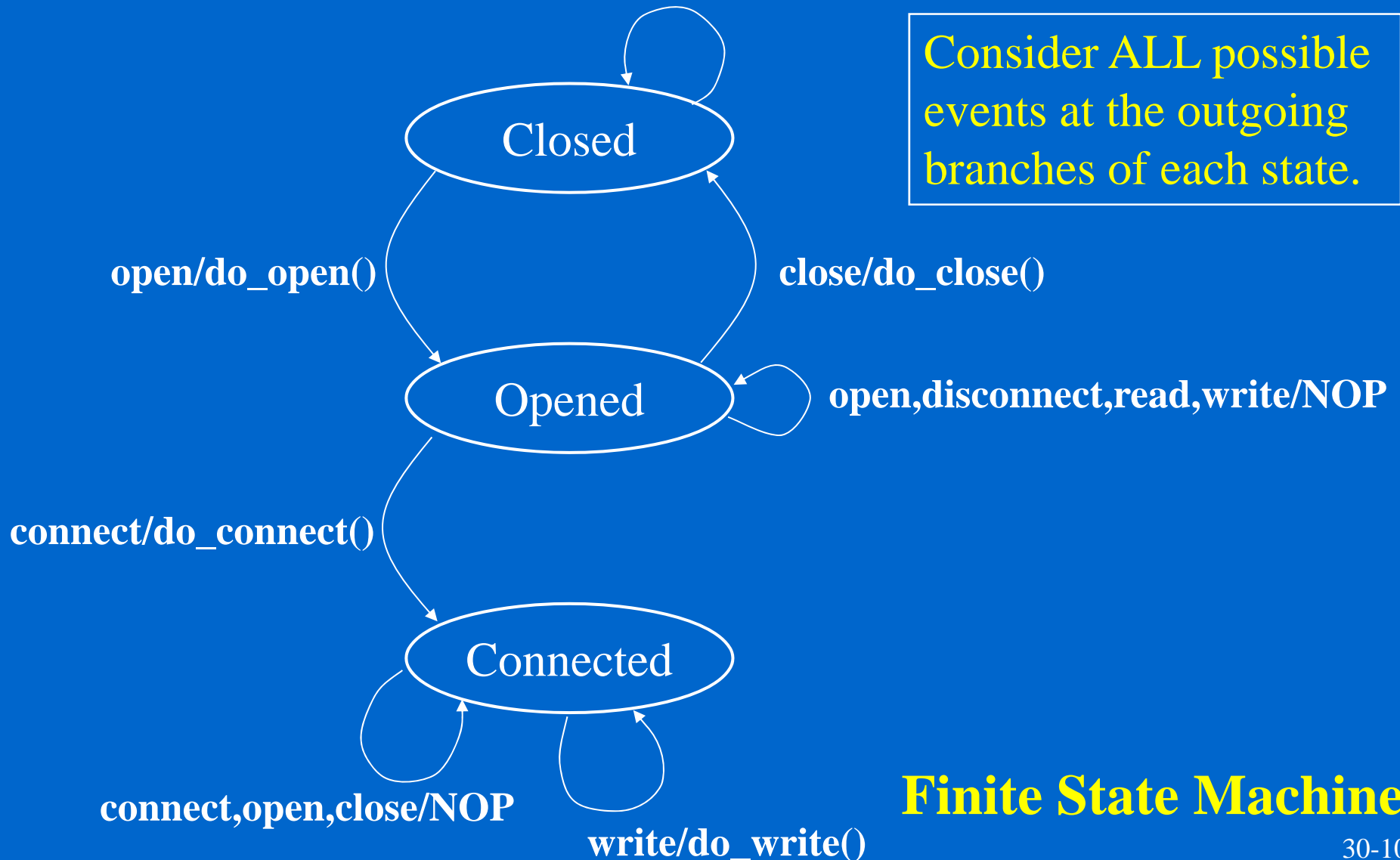
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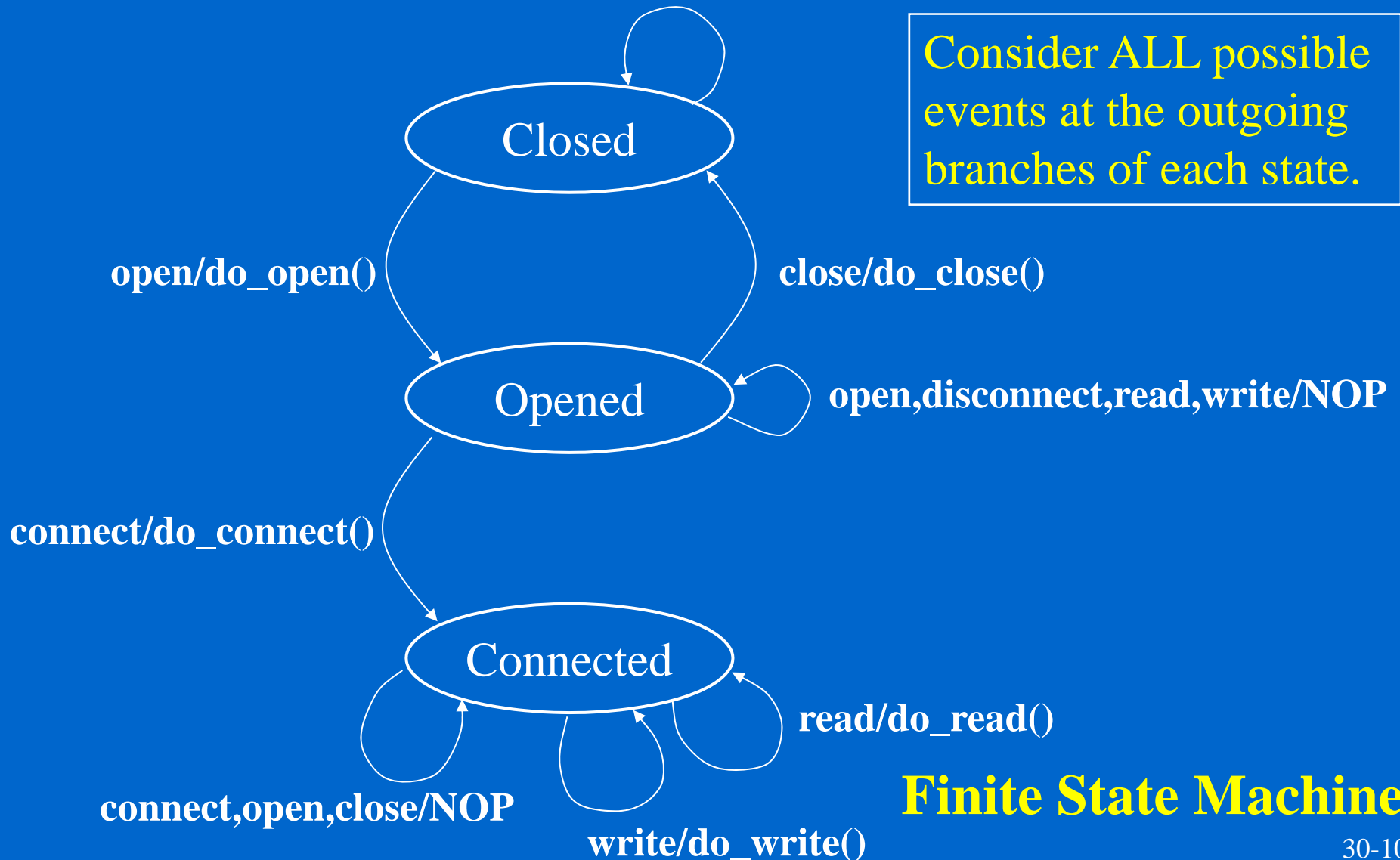


Finite State Machine

State Diagram

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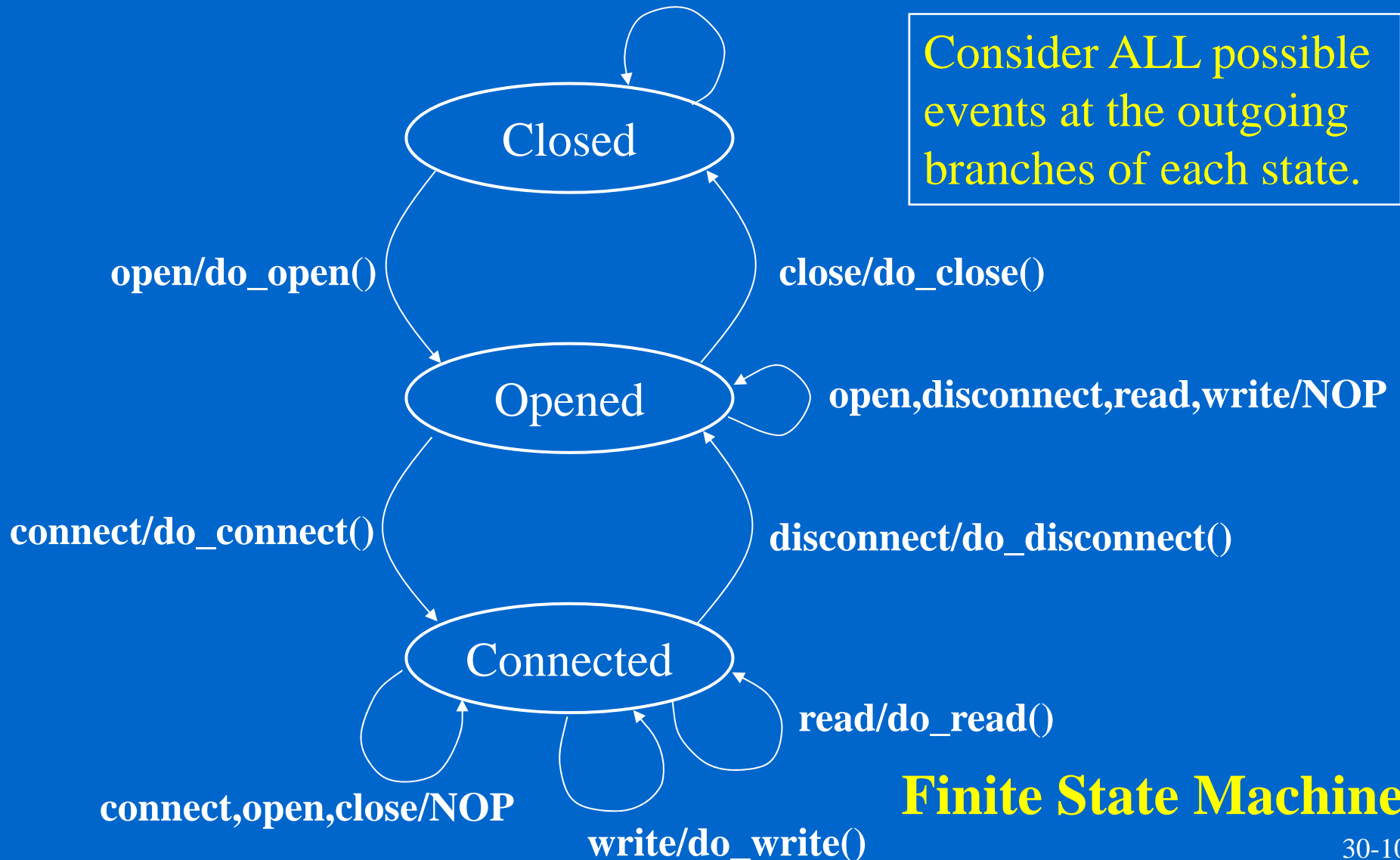


Finite State Machine

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Finite State Machine

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- ★ Simplify the considerations of server program logics.

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- ❖ A control flow diagram of the client simply does not show all possible ways of usages.

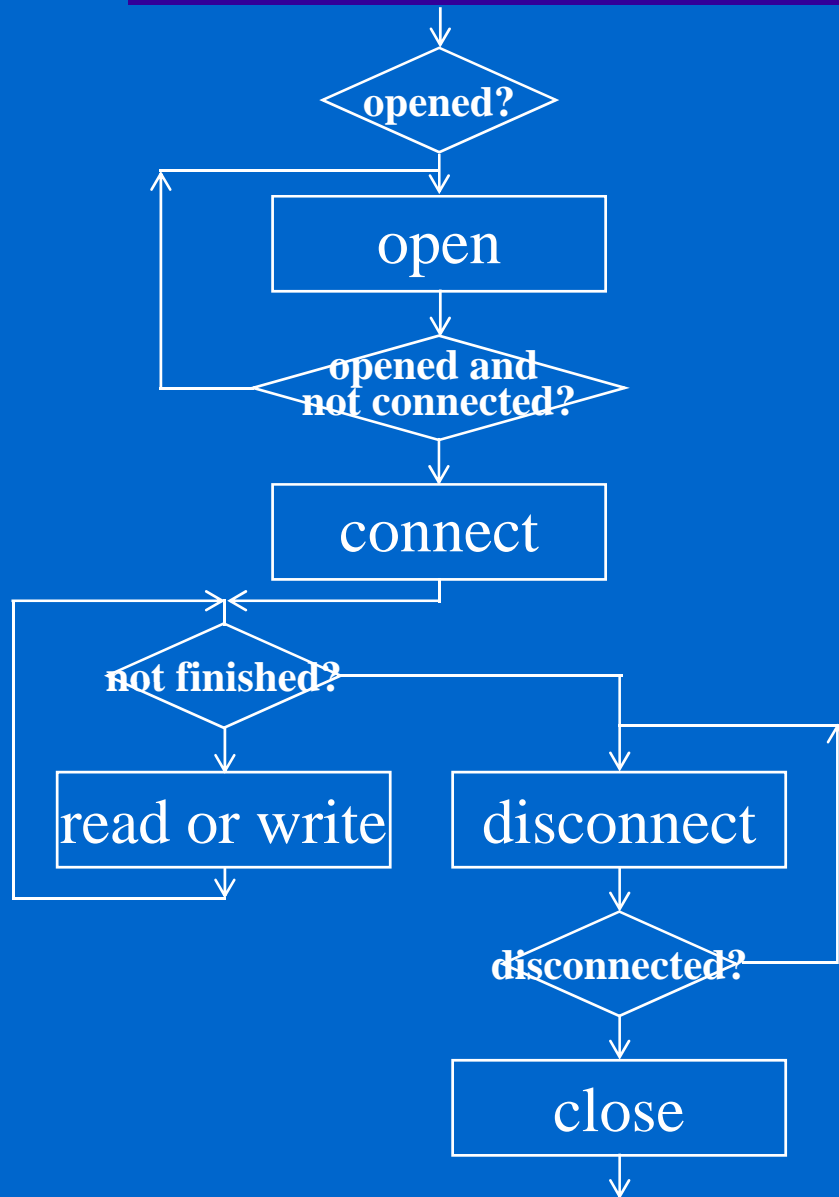
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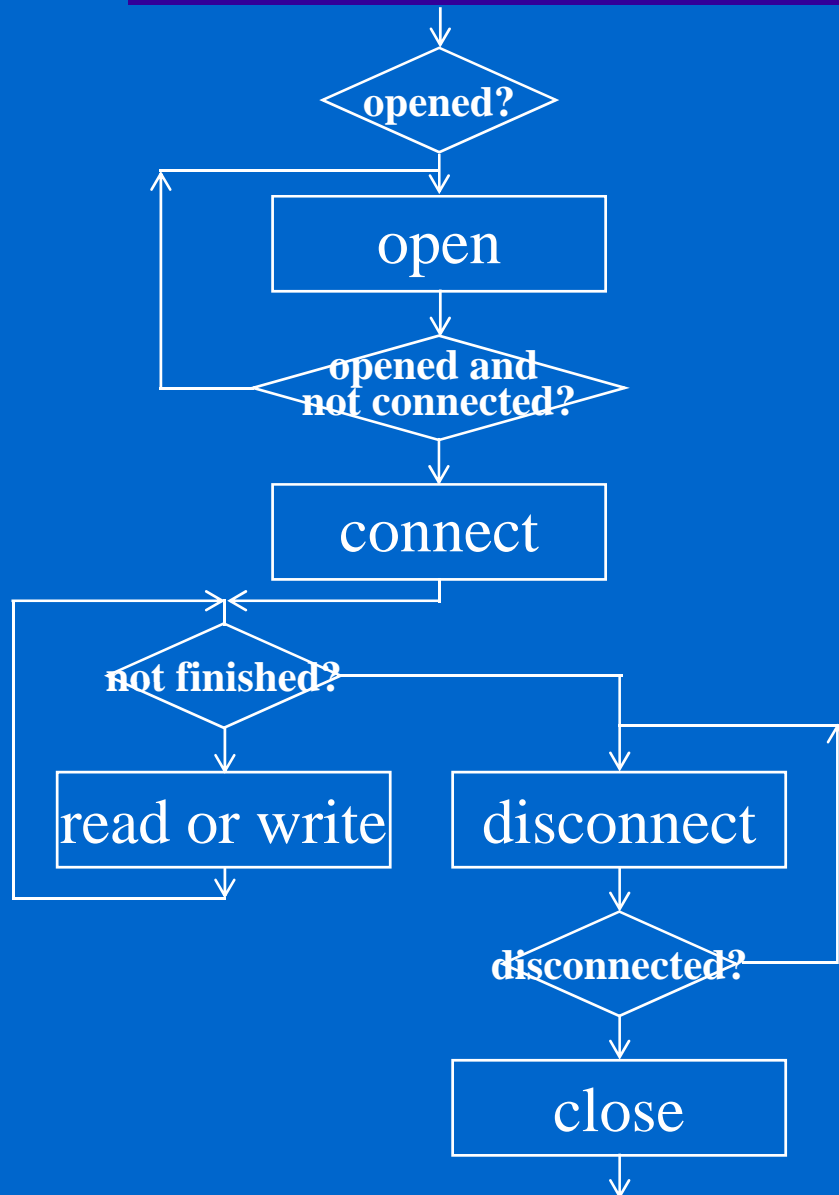
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See the following example...

Control Flow Diagram of A Client

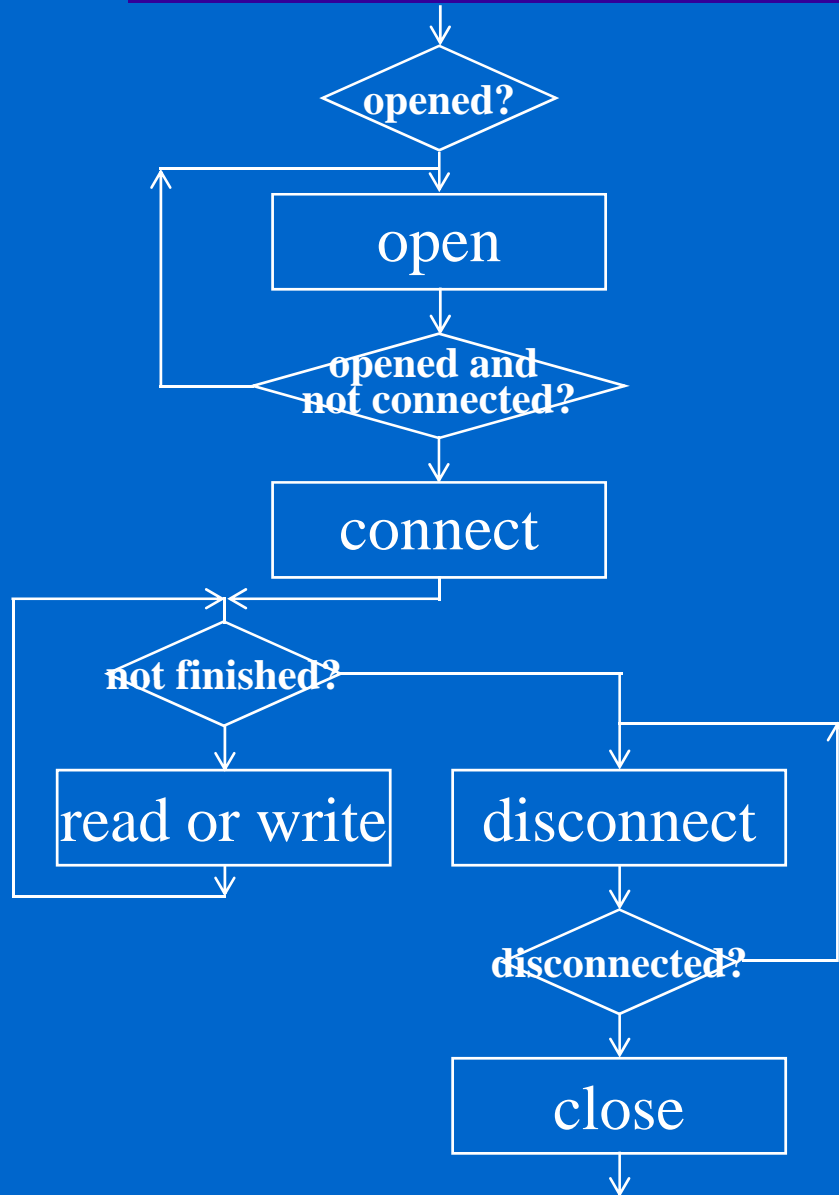


Control Flow Diagram of A Client



- ✧ This is the control flow for the **TYPICAL / CORRECT** usage of this NetCommStream object.

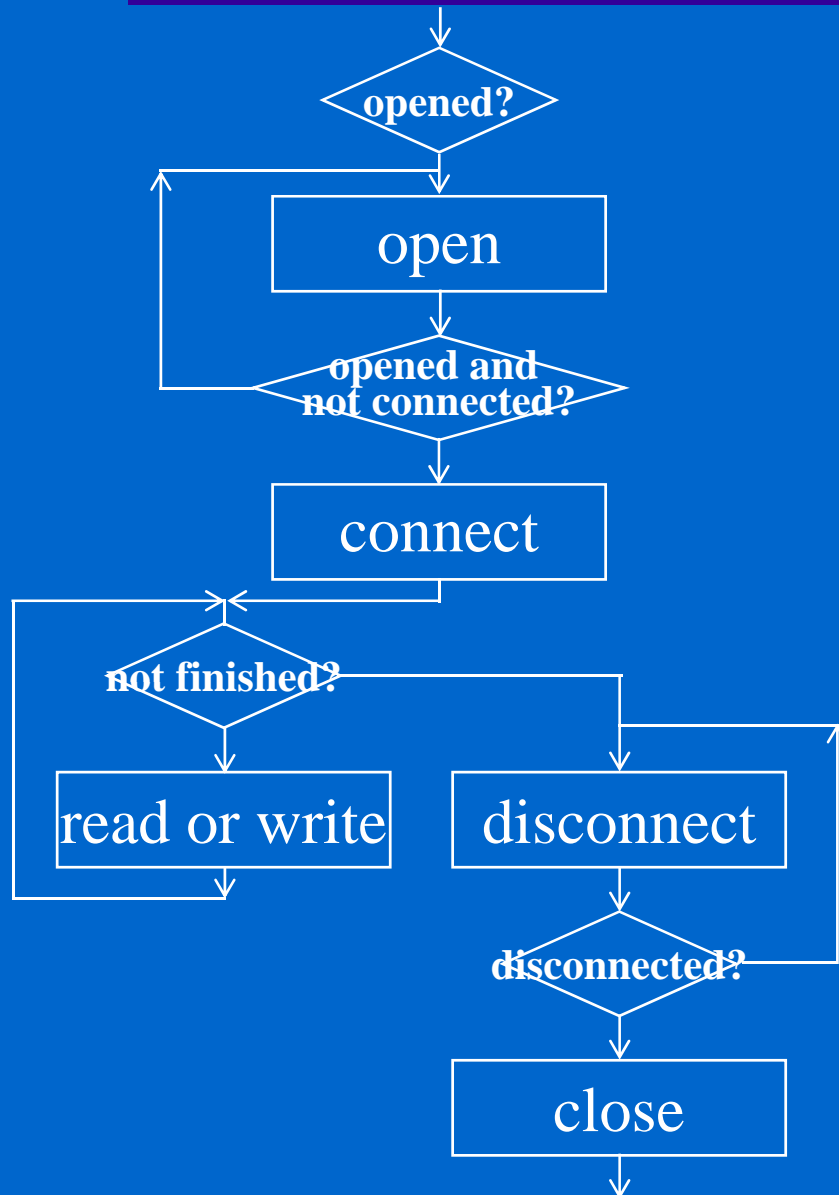
Control Flow Diagram of A Client



✧ This is the control flow for the TYPICAL / CORRECT usage of this NetCommStream object.

✧ **Problems:**

Control Flow Diagram of A Client

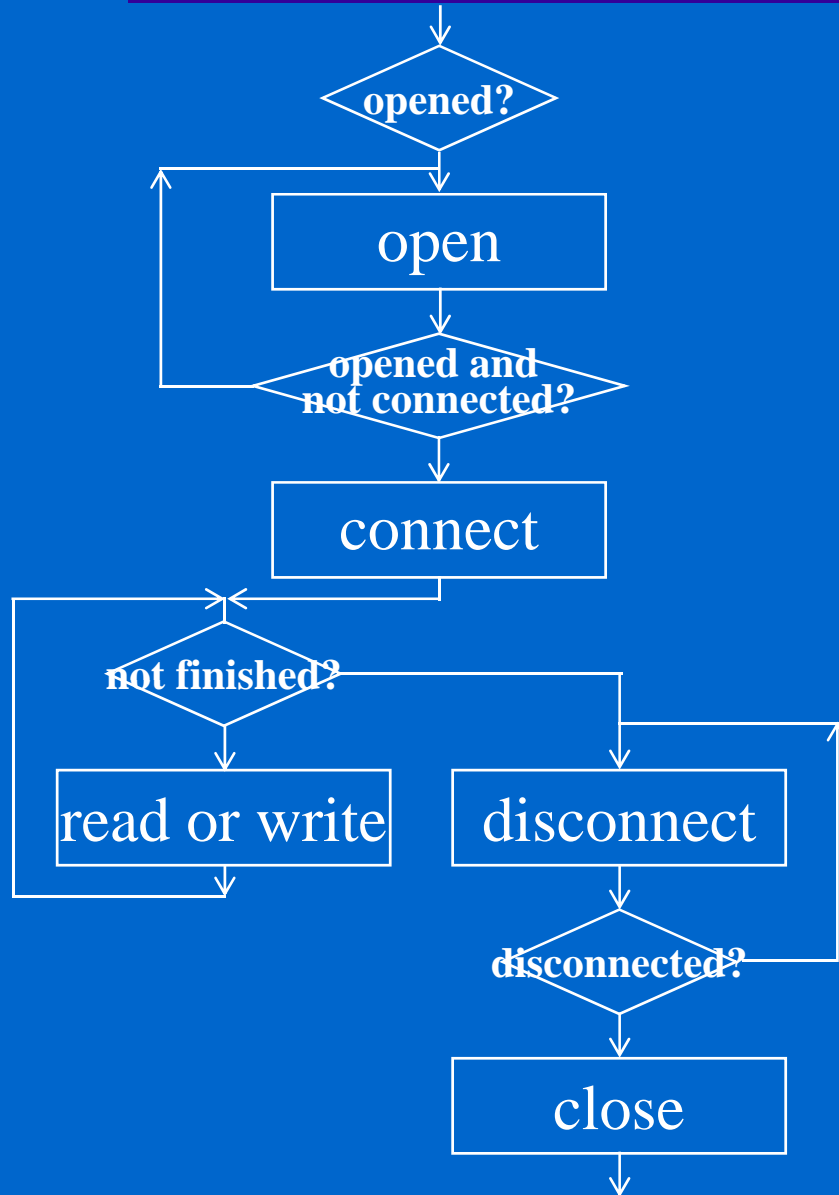


✧ This is the control flow for the TYPICAL / CORRECT usage of this NetCommStream object.

✧ Problems:

- ★ What if the client does not follow this advised procedure?
Eg. Not opened but do the connect at the first step? Not connected but do the read/write at the second step?

Control Flow Diagram of A Client



✧ This is the control flow for the **TYPICAL / CORRECT** usage of this NetCommStream object.

✧ Problems:

- ★ What if the client does not follow this advised procedure?
Eg. Not opened but do the connect at the first step? Not connected but do the read/write at the second step?
- ★ What if there are other possible usage patterns?
e.g. Opened but find no peer to connect and then close immediately.
Disconnected but find some other peer to connect.

Implementation of an FSM

- ❖ Use a single *enum* type of variable to represent the state of the system
enum InternalStates {*Closed, Opened, Connected*};
InternalStates **m_state**;
- ❖ In an OO system, objects communicate with each other through events.
Take the event **open** and its handler **open()** as example:

1. For each **open** message of each state in the diagram
2. Implement the response in **open()**

```
void open() {  
    if (m_state == Closed) {  
        do_open();  
        m_state = Opened;  
    }  
    else if (m_state == Opened) ;  
    else if (m_state == Connected) ;  
}
```

**A systematic way of
implementation for
a state diagram**

Implementation (cont'd)

```
void close() {  
    if (m_state == Opened ) {  
        do_close();  
        m_state = Closed;  
    }  
}
```

Implementation (cont'd)

```
void close() {  
    if (m_state == Opened ) {  
        do_close();  
        m_state = Closed;  
    }  
}
```

```
void connect() {  
    if (m_state == Opened ) {  
        do_connect();  
        m_state = Connected;  
    }  
}
```

Implementation (cont'd)

```
void close() {  
    if (m_state == Opened ) {  
        do_close();  
        m_state = Closed;  
    }  
}  
  
void connect() {  
    if (m_state == Opened ) {  
        do_connect();  
        m_state = Connected;  
    }  
}  
  
void disconnect() {  
    if (m_state == Connected ) {  
        do_disconnect();  
        m_state = Opened;  
    }  
}
```

Implementation (cont'd)

```
void close() {  
    if (m_state == Opened ) {  
        do_close();  
        m_state = Closed;  
    }  
}
```

```
void connect() {  
    if (m_state == Opened ) {  
        do_connect();  
        m_state = Connected;  
    }  
}
```

```
void disconnect() {  
    if (m_state == Connected ) {  
        do_disconnect();  
        m_state = Opened;  
    }  
}
```

```
void read() {  
    if (m_state == Connected )  
        do_read();  
}
```

Implementation (cont'd)

```
void close() {
    if (m_state == Opened ) {
        do_close();
        m_state = Closed;
    }
}

void connect() {
    if (m_state == Opened ) {
        do_connect();
        m_state = Connected;
    }
}

void disconnect() {
    if (m_state == Connected ) {
        do_disconnect();
        m_state = Opened;
    }
}
```

```
void read() {
    if (m_state == Connected )
        do_read();
}

void write() {
    if (m_state == Connected )
        do_write();
}
```

Modification over State Diagram

- ✧ If the system specification is modified such that it is allowed to **close** at the **Connected** state

Modification over State Diagram

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Closed

Opened

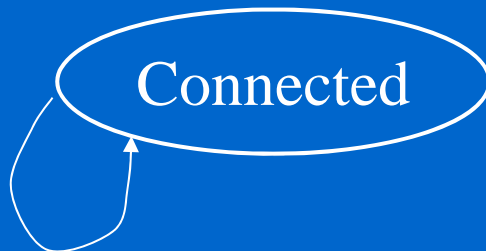
Connected

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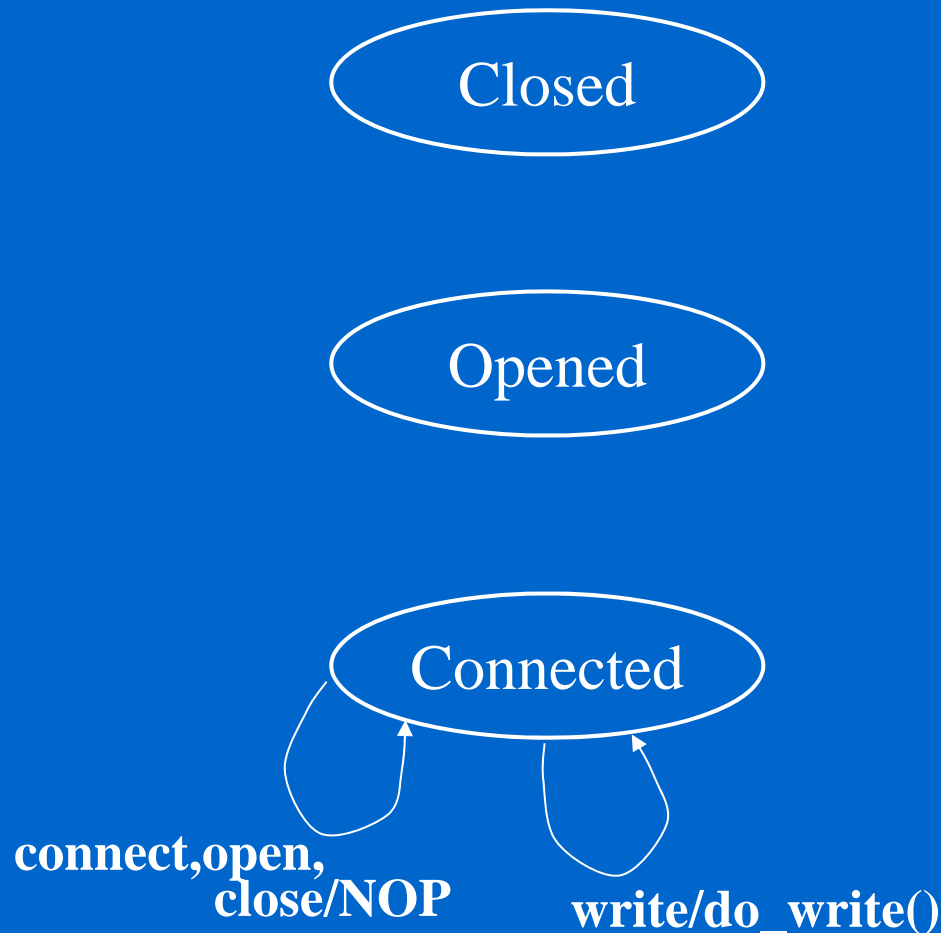
Opened



connect,open,
close/NOP

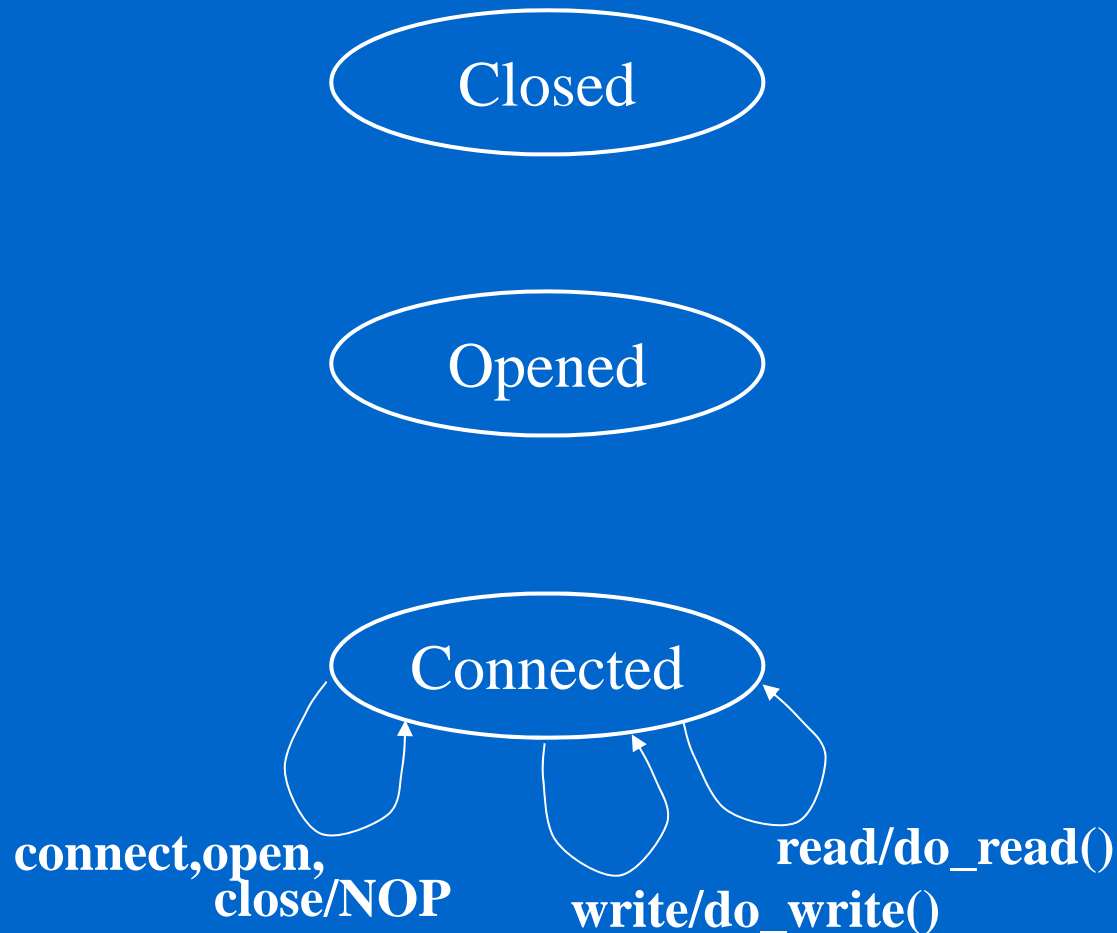
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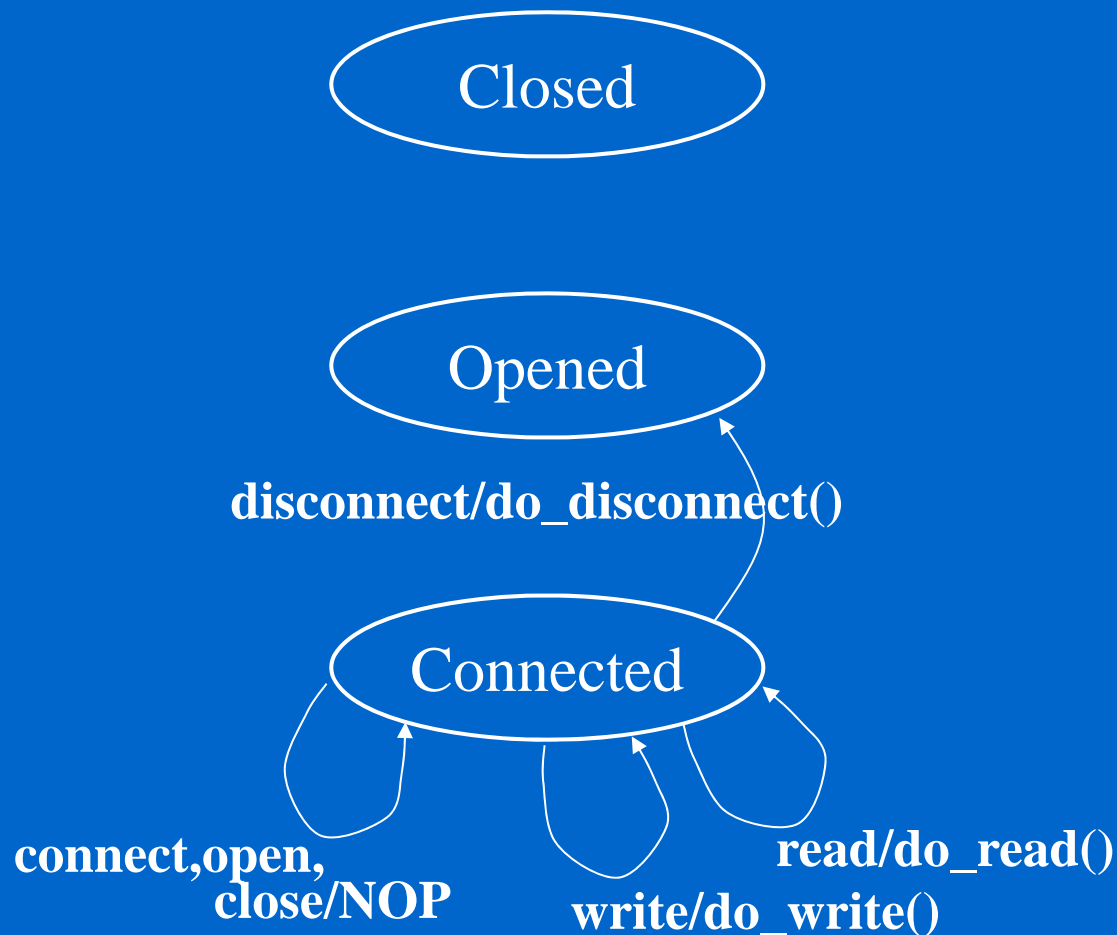
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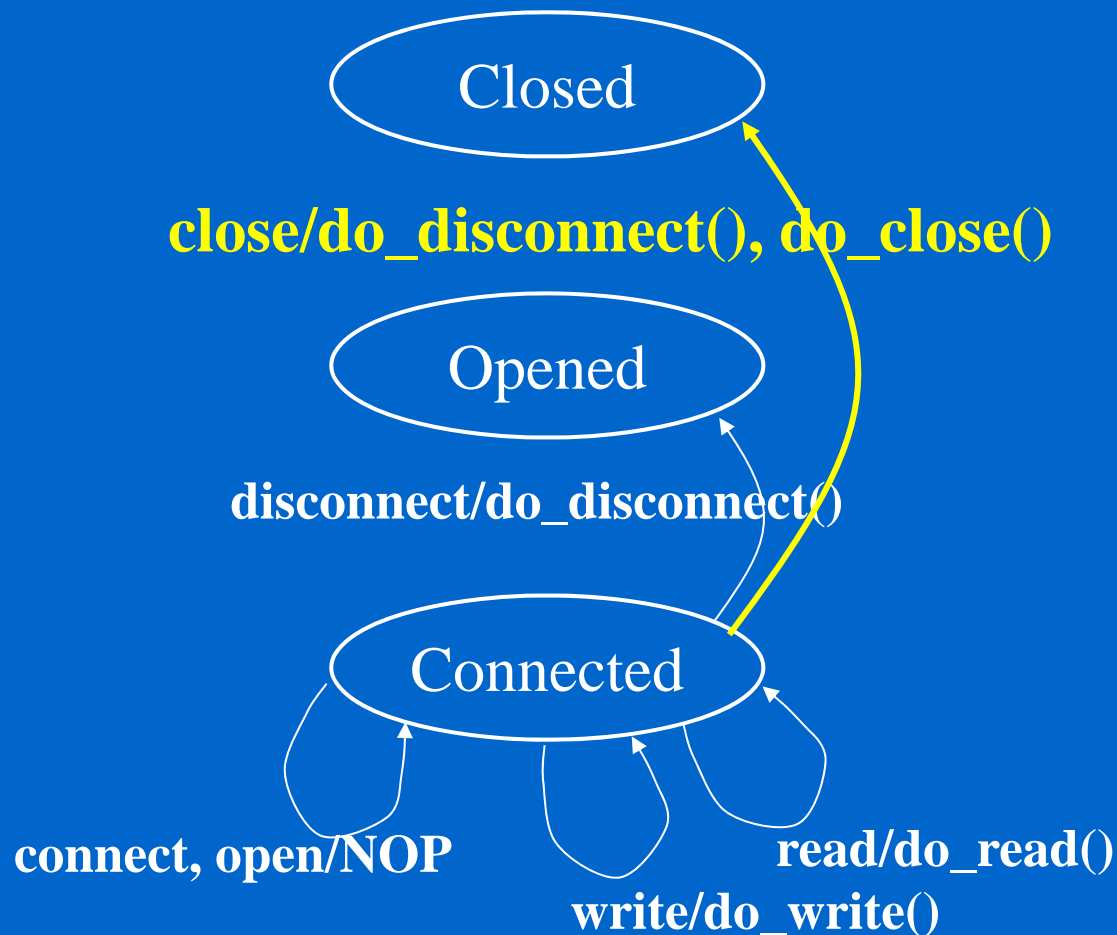
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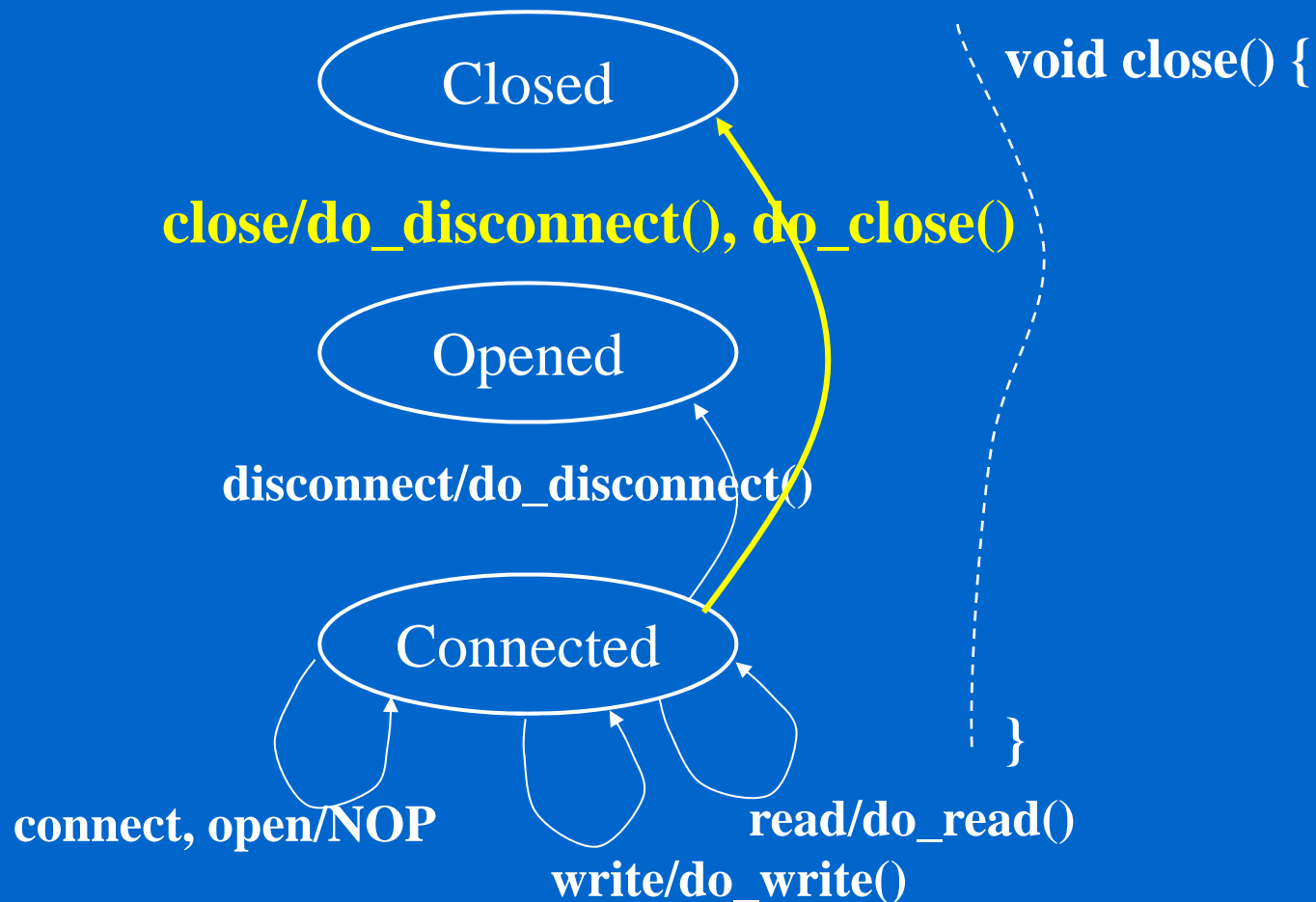
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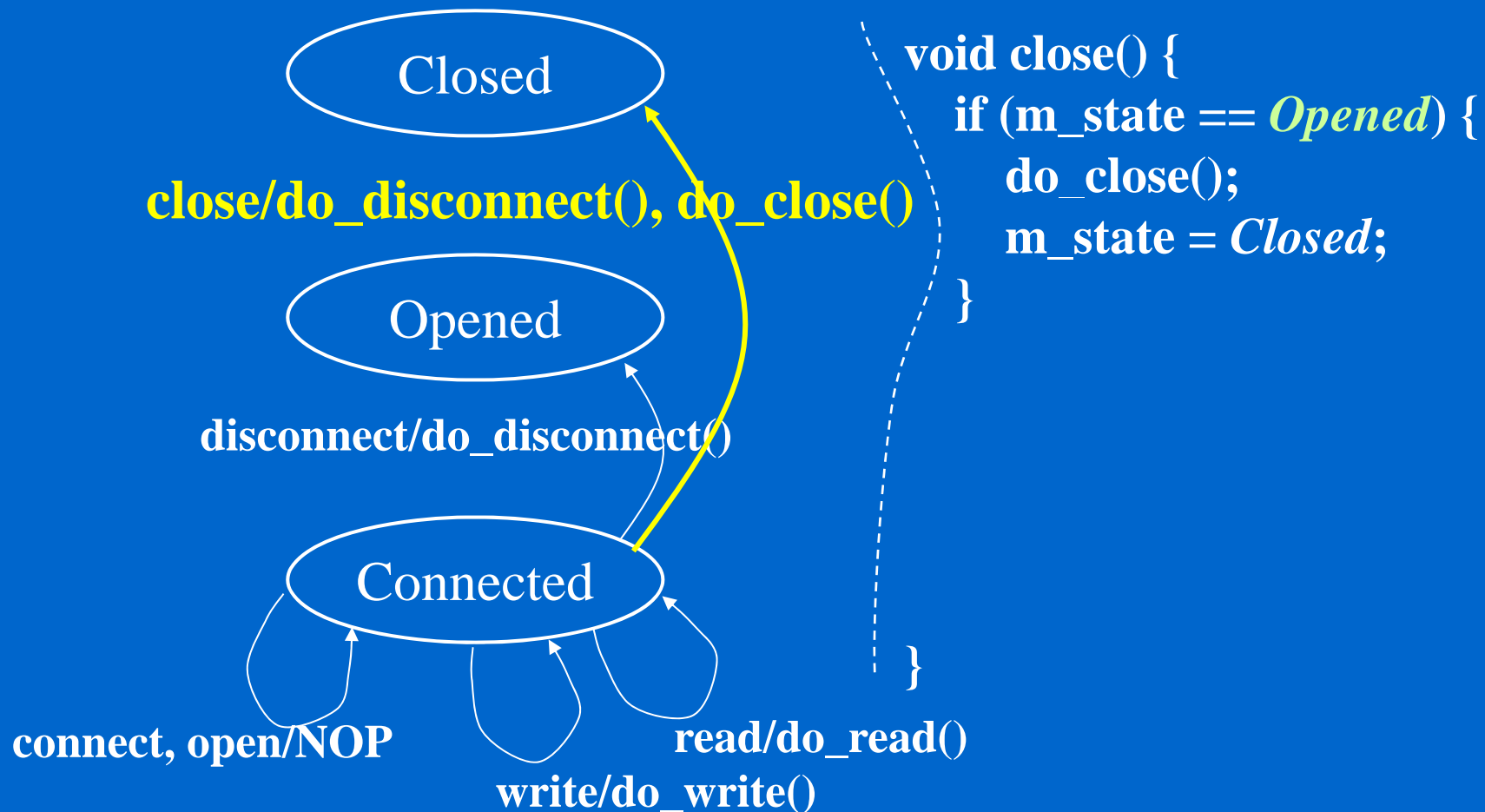
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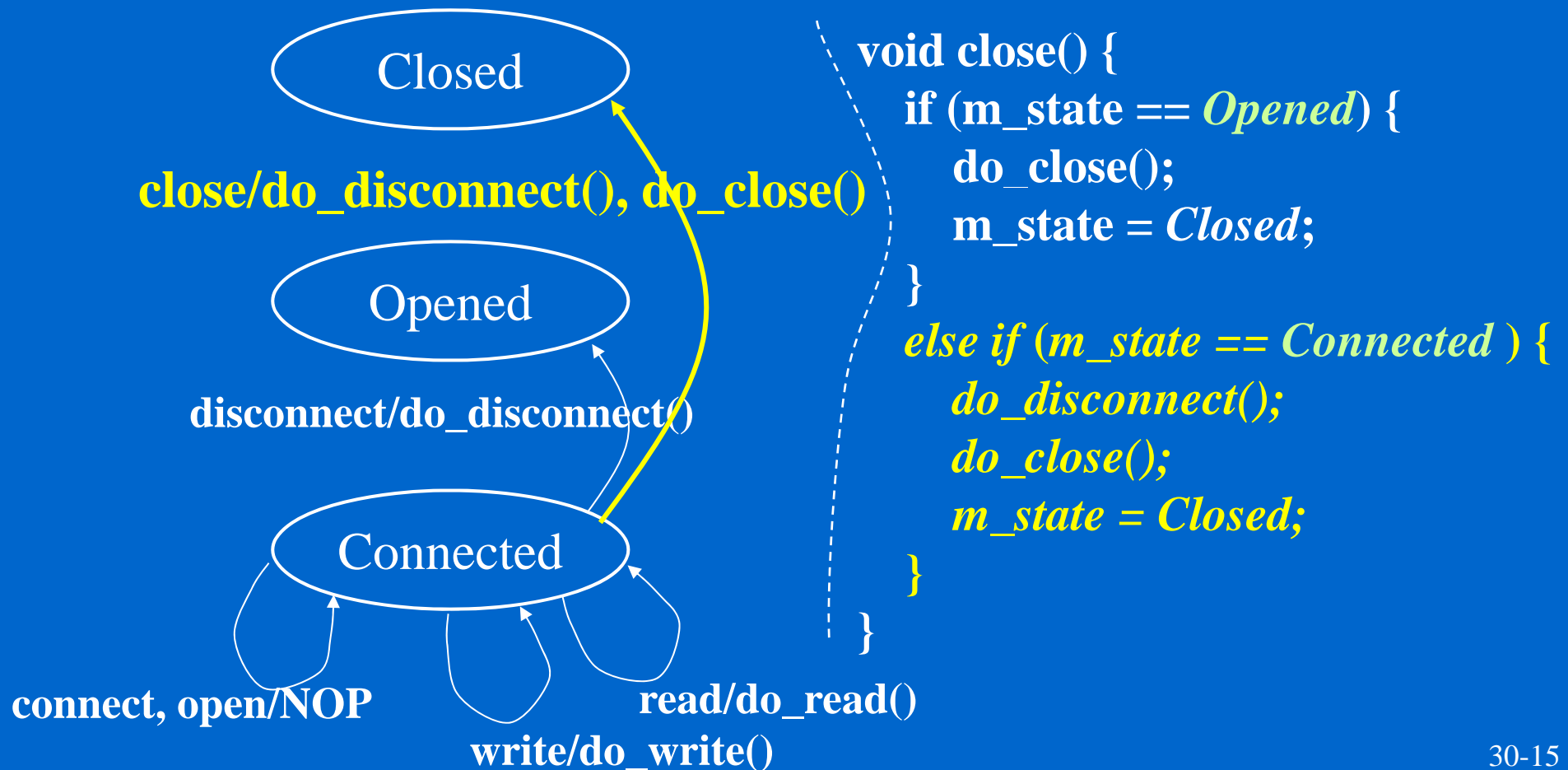
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Second Implementation

- ✧ Use two *enum* types for the **state** of the system and the **event**

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Second Implementation

- ✧ Use two *enum* types for the **state** of the system and the **event**

```
enum State { Closed, Opened, Connected };
```

```
enum Event { open, connect, read, write, disconnect, close };
```

- ✧ Implement all actions as functions

```
void do_open() { ... }
```

```
void do_connect() { ... }
```

```
void do_read() { ... }
```

```
void do_close() { ... }
```

```
void do_disconnect() { ... }
```

```
void do_write() { ... }
```

Second Implementation

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enum **State** { *Closed, Opened, Connected* };
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- ✧ Implement all actions as functions

```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- ✧ Use a static **state** variable inside the Transition function

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```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- Use a static **state** variable inside the Transition function

```
void Transition(Event event) {
```

```
}
```

Second Implementation

- ❖ Use two *enum* types for the **state** of the system and the **event**

```
enum State { Closed, Opened, Connected };  
enum Event { open, connect, read, write, disconnect, close };
```

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```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- ❖ Use a static **state** variable inside the Transition function

```
void Transition(Event event) {  
    static State state = Closed;
```

```
}
```

Second Implementation

- ❖ Use two *enum* types for the **state** of the system and the **event**

```
enum State { Closed, Opened, Connected };
```

```
enum Event { open, connect, read, write, disconnect, close };
```

- ❖ Implement all actions as functions

```
void do_open() { ... }
```

```
void do_close() { ... }
```

```
void do_connect() { ... }
```

```
void do_disconnect() { ... }
```

```
void do_read() { ... }
```

```
void do_write() { ... }
```

- ❖ Use a static **state** variable inside the Transition function

```
void Transition(Event event) {  
    static State state = Closed;  
    switch (state) {
```

```
    }  
}
```


Second Implementation

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enum **State** { *Closed, Opened, Connected* };
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- Implement all actions as functions

```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- Use a static **state** variable inside the Transition function

```
void Transition(Event event) {  
    static State state = Closed;  
    switch (state) {  
        case Closed:  
  
  
  
  
  
  
  
  
  
        case Connected:  
  
  
    }  
}
```

case *Opened*:

Second Implementation

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- Implement all actions as functions

```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- Use a static **state** variable inside the Transition function

```
void Transition(Event event) {  
    static State state = Closed;  
    switch (state) {  
        case Closed:  
            switch (event) {  
                case open:  
                    do_open(); state = Opened;  
            } break;  
        case Opened:  
            case Connected:  
    }  
}
```

Second Implementation

- Use two *enum* types for the **state** of the system and the **event**

```
enum State { Closed, Opened, Connected };  
enum Event { open, connect, read, write, disconnect, close };
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- Implement all actions as functions

```
void do_open() { ... }           void do_close() { ... }  
void do_connect() { ... }       void do_disconnect() { ... }  
void do_read() { ... }          void do_write() { ... }
```

- Use a static **state** variable inside the Transition function

```
void Transition(Event event) {  
    static State state = Closed;  
    switch (state) {  
    case Closed:  
        switch (event) {  
        case open:  
            do_open(); state = Opened;  
        } break;  
    case Opened:
```

```
        switch (event) {  
        case connect:  
            ...  
        case close:  
            ...  
        } break;  
    case Connected:  
        ...  
    }  
}
```

OO Way – the **State** Pattern

NetConnection

+do_open()

+do_close()

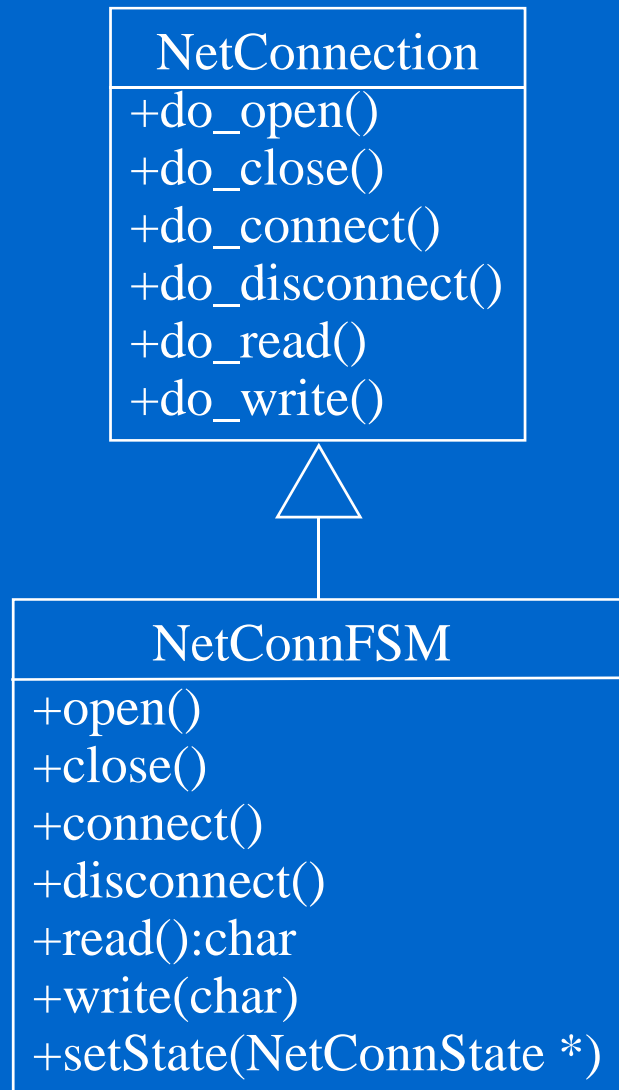
+do_connect()

+do_disconnect()

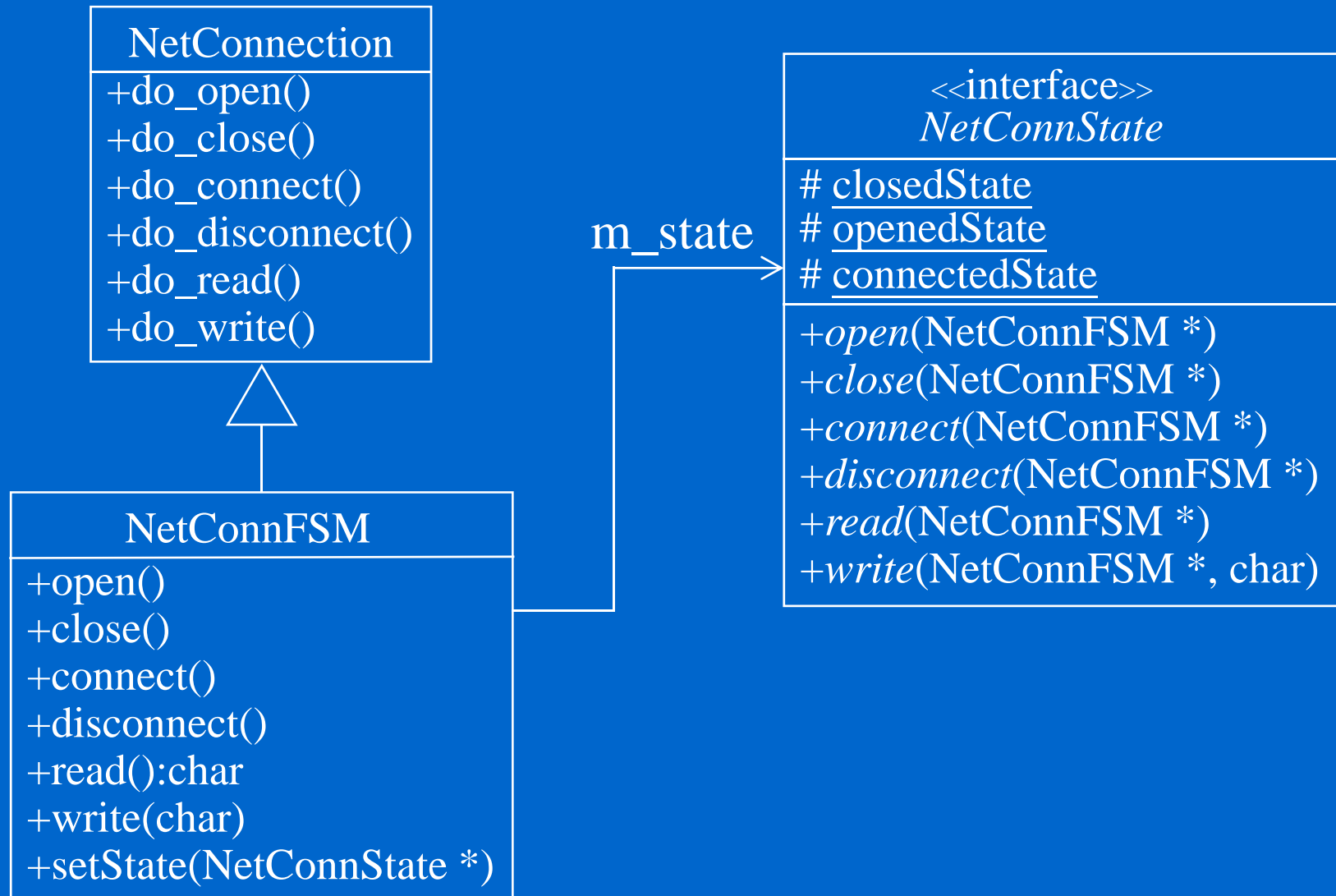
+do_read()

+do_write()

OO Way – the **State** Pattern

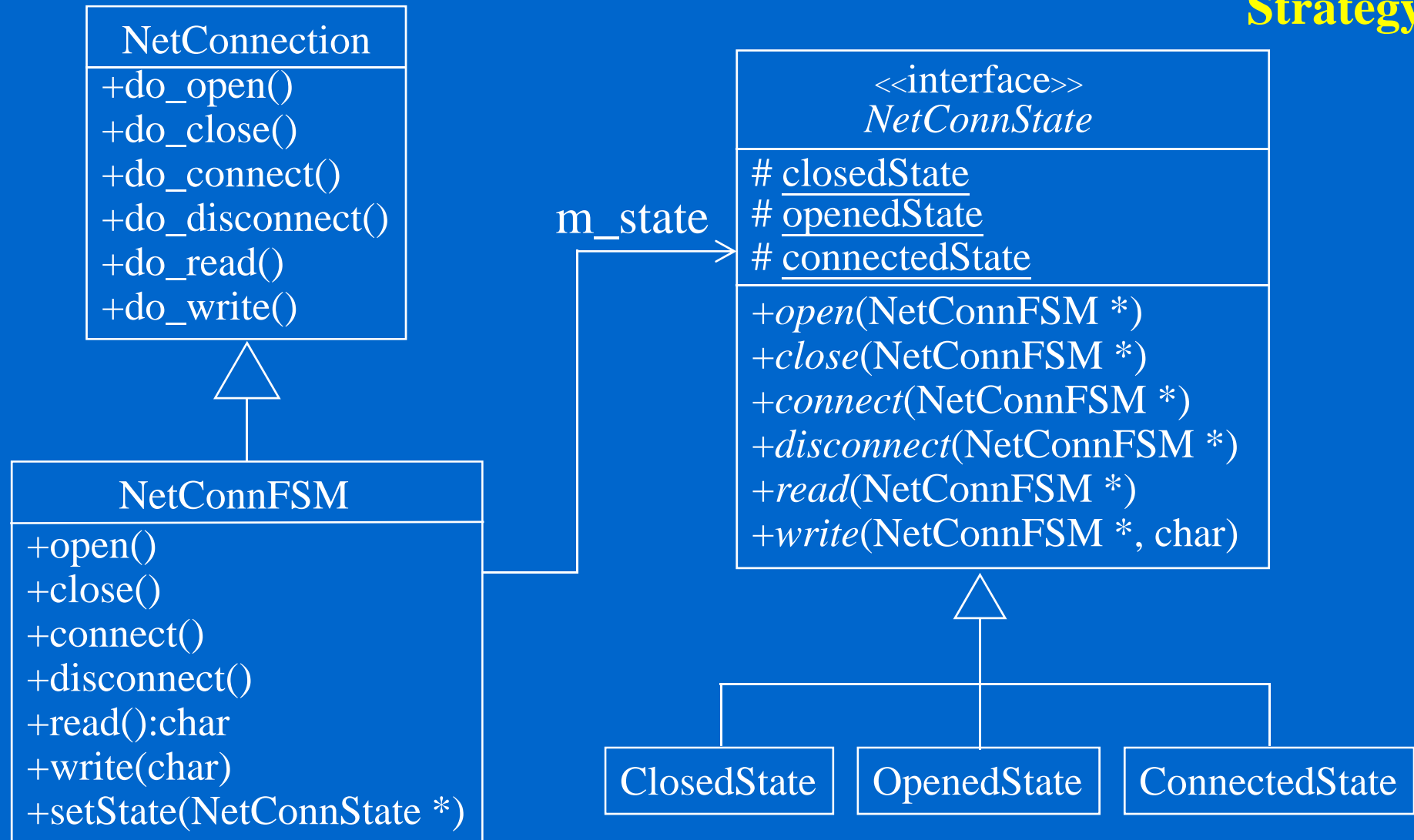


OO Way – the **State** Pattern



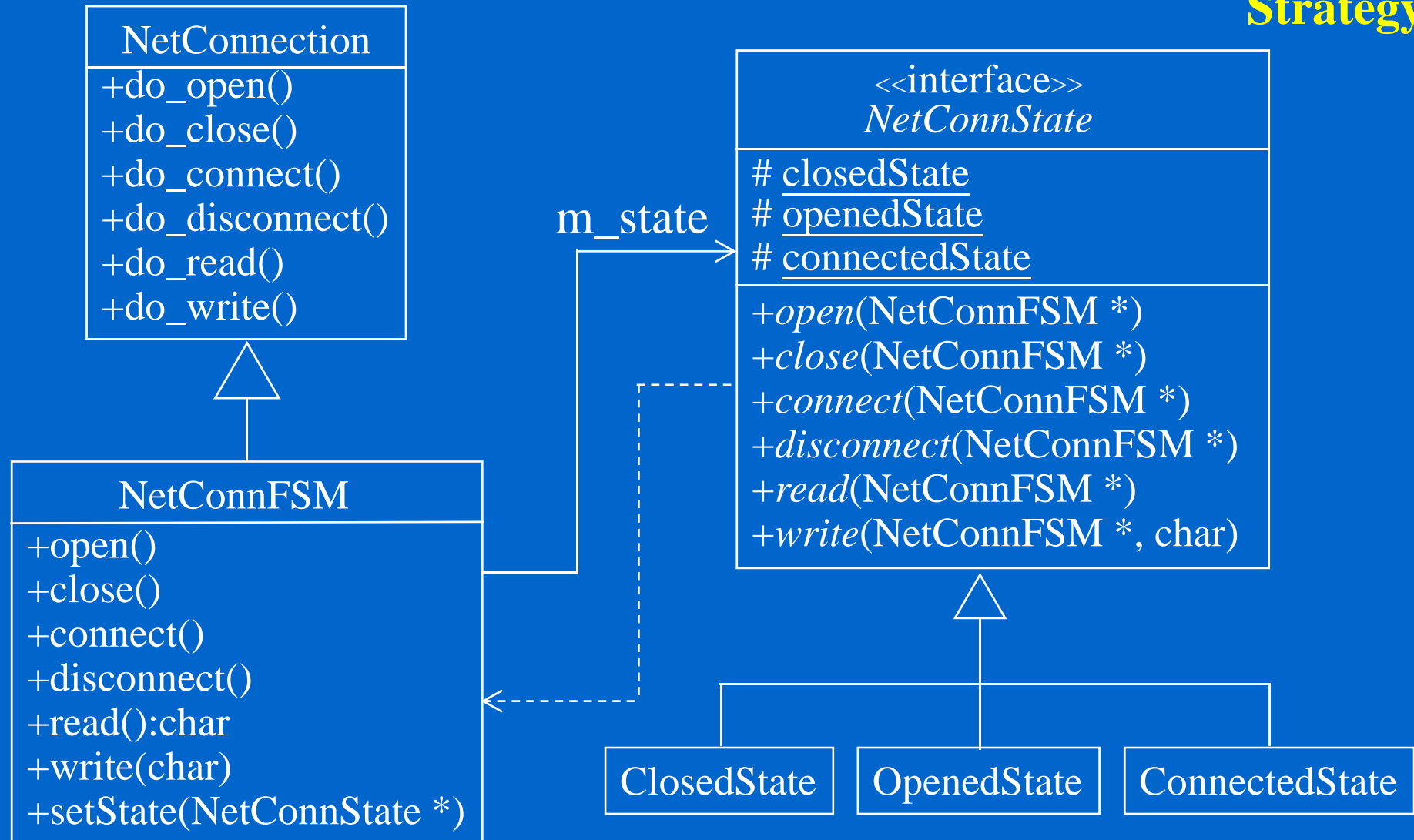
OO Way – the **State** Pattern

Strategy



OO Way – the **State** Pattern

Strategy



Implementation (1/4)

- ✧ Actual network operations

Implementation (1/4)

❖ Actual network operations

```
class NetConnection {  
public:  
    void do_open() { ... }  
    void do_connect() { ... }  
    char do_read() { ... }  
};  
    void do_close() { ... }  
    void do_disconnect() { ... }  
    void do_write(char x) { ... }
```

Implementation (1/4)

❖ Actual network operations

```
class NetConnection {  
public:  
    void do_open() { ... }  
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    char do_read() { ... }  
};  
    void do_close() { ... }  
    void do_disconnect() { ... }  
    void do_write(char x) { ... }
```

❖ Interface for all states

Implementation (1/4)

❖ Actual network operations

```
class NetConnection {  
public:  
    void do_open() { ... }           void do_close() { ... }  
    void do_connect() { ... }       void do_disconnect() { ... }  
    char do_read() { ... }          void do_write(char x) { ... }  
};
```

❖ Interface for all states

```
class NetConnState {  
public:  
    virtual void open(NetConnFSM *) = 0; virtual void close(NetConnFSM *);  
    virtual void connect(NetConnFSM *); virtual void disconnect(NetConnFSM *);  
    virtual char read(NetConnFSM *); virtual void write(NetConnFSM *, char);  
protected:  
    static ClosedState closedState;  
    static OpenedState openedState;  
    static ConnectedState connectedState;  
};
```

Implementation (1/4)

❖ Actual network operations

```
class NetConnection {
public:
    void do_open() { ... }           void do_close() { ... }
    void do_connect() { ... }       void do_disconnect() { ... }
    char do_read() { ... }          void do_write(char x) { ... }
};
```

❖ Interface for all states

```
class NetConnState {
public:
    virtual void open(NetConnFSM *) = 0; virtual void close(NetConnFSM *);
    virtual void connect(NetConnFSM *); virtual void disconnect(NetConnFSM *);
    virtual char read(NetConnFSM *);    virtual void write(NetConnFSM *, char);
protected:
    static ClosedState closedState;
    static OpenedState openedState;
    static ConnectedState connectedState;
};
```

Singleton

```
ClosedState NetConnState::closedState;
OpenedState NetConnState::openedState;
ConnectedState NetConnState::
```

connectedState; 30-18

Implementation (2/4)

✧ the Finite State Machine

Implementation (2/4)

❖ the Finite State Machine

```
class NetConnFSM: public NetConnection {
public:
    NetConnFSM():m_state(&closedState) {}
    void setState(NetConnState *s) { m_state = s; }
    void open() { m_state->open(this); }
    void close() { m_state->close(this); }
    void connect() { m_state->connect(this); }
    void disconnect() { m_state->disconnect(this); }
    char read() { return m_state->read(this); }
    void write(char x) { m_state->write(this, x); }
private:
    NetConnState *m_state;
};
```

Implementation (2/4)

❖ the Finite State Machine

```
class NetConnFSM: public NetConnection {  
public:  
    NetConnFSM():m_state(&closedState) { }  
    void setState(NetConnState *s) { m_state = s; }  
    void open() { m_state->open(this); }  
    void close() { m_state->close(this); }  
    void connect() { m_state->connect(this); }  
    void disconnect() { m_state->disconnect(this); }  
    char read() { return m_state->read(this); }  
    void write(char x) { m_state->write(this, x); }  
private:  
    NetConnState *m_state;  
};
```



Strategy, delegation of events
Closed for modification

Implementation (2/4)

❖ the Finite State Machine

```
class NetConnFSM: public NetConnection {  
public:  
    NetConnFSM():m_state(&closedState) { }  
    void setState(NetConnState *s) { m_state = s; }  
    void open() { m_state->open(this); }  
    void close() { m_state->close(this); }  
    void connect() { m_state->connect(this); }  
    void disconnect() { m_state->disconnect(this); }  
    char read() { return m_state->read(this); }  
    void write(char x) { m_state->write(this, x); }  
private:  
    NetConnState *m_state;  
};
```

❖ Usage:

Strategy, delegation of events
Closed for modification

Implementation (2/4)

❖ the Finite State Machine

```
class NetConnFSM: public NetConnection {  
public:  
    NetConnFSM():m_state(&closedState) {}  
    void setState(NetConnState *s) { m_state = s; }  
    void open() { m_state->open(this); }  
    void close() { m_state->close(this); }  
    void connect() { m_state->connect(this); }  
    void disconnect() { m_state->disconnect(this); }  
    char read() { return m_state->read(this); }  
    void write(char x) { m_state->write(this, x); }  
private:  
    NetConnState *m_state;  
};
```

Strategy, delegation of events
Closed for modification

❖ Usage:

```
void main() {  
    NetConnFSM conn_obj;  
    conn_obj.open();  
    conn_obj.connect();  
    int x=conn_obj.read();  
    ...  
    conn_obj.write(x);  
    ...  
    conn_obj.disconnect();  
    conn_obj.close();  
}
```

Implementation (2/4)

❖ the Finite State Machine

```
class NetConnFSM: public NetConnection {  
public:  
    NetConnFSM():m_state(&closedState) {}  
    void setState(NetConnState *s) { m_state = s; }  
    void open() { m_state->open(this); }  
    void close() { m_state->close(this); }  
    void connect() { m_state->connect(this); }  
    void disconnect() { m_state->disconnect(this); }  
    char read() { return m_state->read(this); }  
    void write(char x) { m_state->write(this, x); }  
private:  
    NetConnState *m_state;  
};
```

Strategy, delegation of events
Closed for modification

❖ Usage:

```
void main() {  
    NetConnFSM conn_obj;  
    conn_obj.open();  
    conn_obj.connect();  
    int x=conn_obj.read();  
    ...  
    conn_obj.write(x);  
    ...  
    conn_obj.disconnect();  
    conn_obj.close();  
}
```

real event sequence

Implementation (3/4)

❖ Actual states

```
class ClosedState: public NetConnState {  
public:  
    void open(NetConnFSM *fsm) {  
        fsm->do_open();  
        fsm->setState(&openedState);  
    }  
    void connect(NetConnFSM *) {}  
    char read(NetConnFSM *) { return 0; }  
};
```

```
void close(NetConnFSM *) {}
```

```
void disconnect(NetConnFSM *) {}
```

```
void write(NetConnFSM *, char) {}
```

Implementation (3/4)

❖ Actual states

```
class ClosedState: public NetConnState {  
public:  
    void open(NetConnFSM *fsm) {  
        fsm->do_open();  
        fsm->setState(&openedState);  
    }  
    void connect(NetConnFSM *) {}  
    char read(NetConnFSM *) { return 0; }  
};
```

```
class OpenedState: public NetConnState {  
public:  
    void open(NetConnFSM *) {}  
    void close(NetConnFSM *fsm) {  
        fsm->do_close();  
        fsm->setState(&closedState);  
    }  
    char read(NetConnFSM *) { return 0; }  
    void write(NetConnFSM *, char) {}  
};
```

```
void close(NetConnFSM *) {}
```

```
void disconnect(NetConnFSM *) {}  
void write(NetConnFSM *, char) {}
```

```
void connect(NetConnFSM *fsm) {  
    fsm->do_connect();  
    fsm->setState(&connectedState);  
}  
void disconnect(NetConnFSM *) {}
```

Implementation (4/4)

```
class ConnectedState: public NetConnState {
public:
    void open(NetConnFSM *) {}
    void close(NetConnFSM *) {}
    void connect(NetConnFSM *) {}
    void disconnect(NetConnFSM *fsm) {
        fsm->do_disconnect();
        fsm->setState(&openedState);
    }
    char read(NetConnFSM *fsm) {
        return fsm->do_read();
    }
    void write(NetConnFSM *fsm, char x) {
        fsm->do_write(x);
    }
};
```

Implementation (4/4)

```
class ConnectedState: public NetConnState {
public:
    void open(NetConnFSM *) {}
    void close(NetConnFSM *) {}
    void connect(NetConnFSM *) {}
    void disconnect(NetConnFSM *fsm) {
        fsm->do_disconnect();
        fsm->setState(&openedState);
    }
    char read(NetConnFSM *fsm) {
        return fsm->do_read();
    }
    void write(NetConnFSM *fsm, char x) {
        fsm->do_write(x);
    }
};
```

- ❖ Implemented through the “Strategy” and “Singleton” patterns

Implementation (4/4)

```
class ConnectedState: public NetConnState {
public:
    void open(NetConnFSM *) {}
    void close(NetConnFSM *) {}
    void connect(NetConnFSM *) {}
    void disconnect(NetConnFSM *fsm) {
        fsm->do_disconnect();
        fsm->setState(&openedState);
    }
    char read(NetConnFSM *fsm) {
        return fsm->do_read();
    }
    void write(NetConnFSM *fsm, char x) {
        fsm->do_write(x);
    }
};
```

- ❖ Implemented through the “Strategy” and “Singleton” patterns
- ❖ Object Mentor Finite State Machine Compiler for Java/C++ code
<http://www.objectmentor.com/resources/bin/smcJava.zip>